

Superior Clamping and Gripping



Product Information

Plug & Work Portfolio Universal Robots Plug & Work Portfolio Universal Robots – Pneumatic Gripping

Plug & Work Portfolio Universal Robots

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Modular. Flexible. Easy.

Plug & Work Portfolio Universal Robots

The Plug & Work portfolio consists of electrically and pneumatically actuated grippers, quick-change modules and force/moment sensors that are specifically adapted to robot arms from Universal Robots.

Field of application

The components can be used in clean and slightly dirty environments.



Advantages – Your benefits

Comprehensive portfolio consisting of various components and grippers for different applications for fast and easy entry into automation

Pre-assembled gripping unit with robot interface therefore no mounting kits or external valves required

Plug & Work with the interfaces suitable for all robots from Universal Robots

Installation modules for robot control are included in the scope of delivery for fast and easy commissioning

Certified SCHUNK Co-act grippers For quick and easy entry into the world of collaborative applications

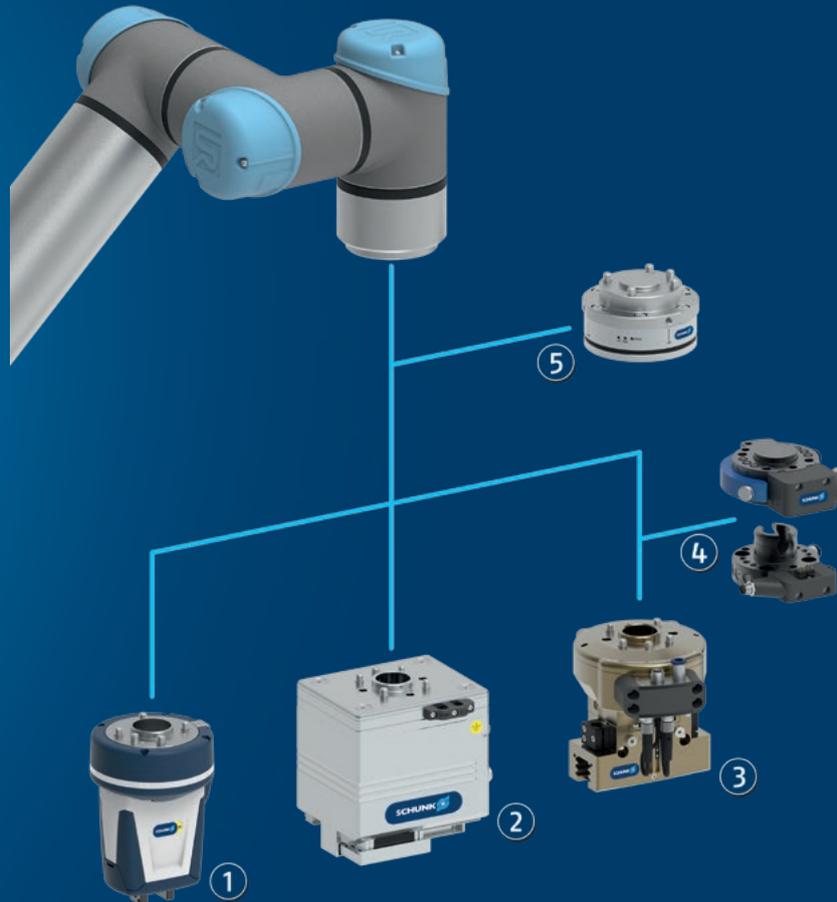
Electric grippers with a long adjustable stroke and force range for flexible workpiece handling

Pneumatic grippers For a high power density and simple integration

Functional description

All the Plug & Work components are prepared for mechanical and electrical direct connection to Universal Robots sizes 3, 5, 10, and 16. Depending on requirements, various grippers and end-of-arm components can be selected.

The pneumatic gripping units are additionally equipped with micro valves meaning no external valves are required.



- ① **Co-act Gripper**
for implementing collaborative applications
- ② **Electric gripper**
for flexible handling of workpieces

- ③ **Pneumatic grippers**
For conventional, robust handling of workpieces
- ④ **Change systems**
for manual exchange of different grippers and actuators
- ⑤ **Force/torque sensor**
for measuring and processing of forces and torques on the robot arm

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General notes about the series

Scope of delivery: Components for direct connection to robots from Universal Robots, assembly and operating manual with declaration of incorporation, USB stick with URcap

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end position for 100 consecutive strokes.

Actuation: Control via digital I/O

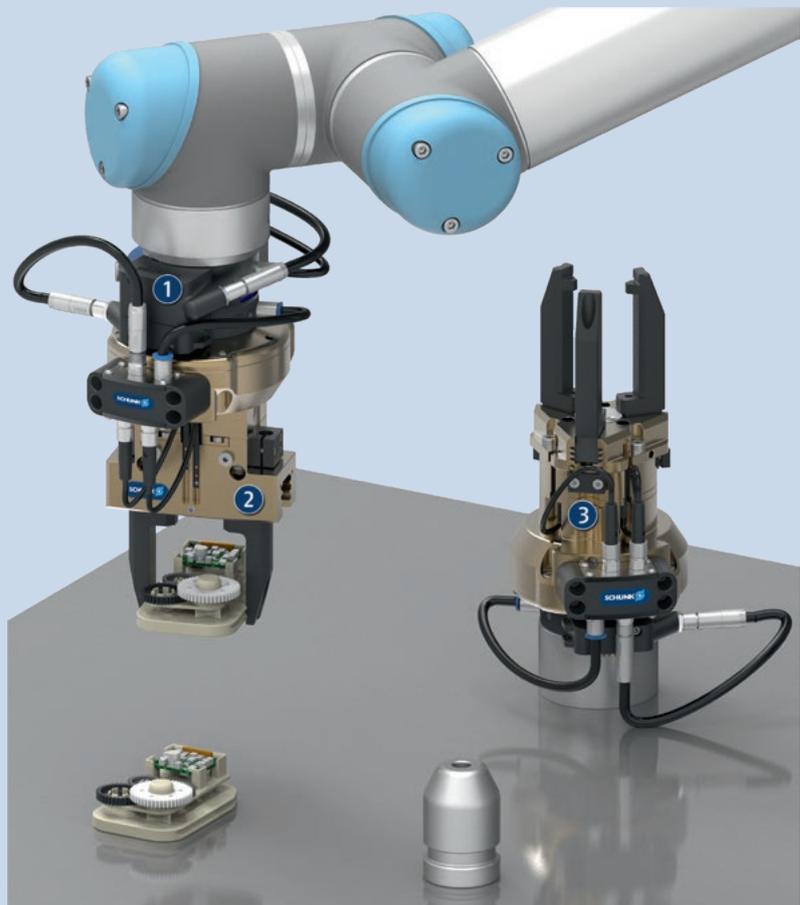
Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g . For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Pneumatic gripping units for Universal Robots for flexible handling of various workpieces. By combining change system and gripping unit, the gripper can be exchanged to suit the workpiece.

- 1 Manual change system SHS
- 2 2-finger parallel gripper PGN-plus-P
- 3 3-finger centric gripper PZN-plus



SCHUNK offers more ...

The following components make the product Plug & Work Portfolio Universal Robots even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Universal intermediate jaw



Jaw quick-change system



Finger blank



Finger blank with jaw quick-change system



Attachment fingers

① For more information on these products can be found on the following product pages or at schunk.com. Please contact us: SCHUNK technical hotline +49-7133-103-2696

Options and special information

Further technical data and accessories: The products from the Plug & Work portfolio represent a selection of SCHUNK standard products that are adapted for direct use with the respective robots. Further technical data and usable accessories for the individual Plug & Work components are therefore included in the product information for the respective SCHUNK standard components.

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Technical data

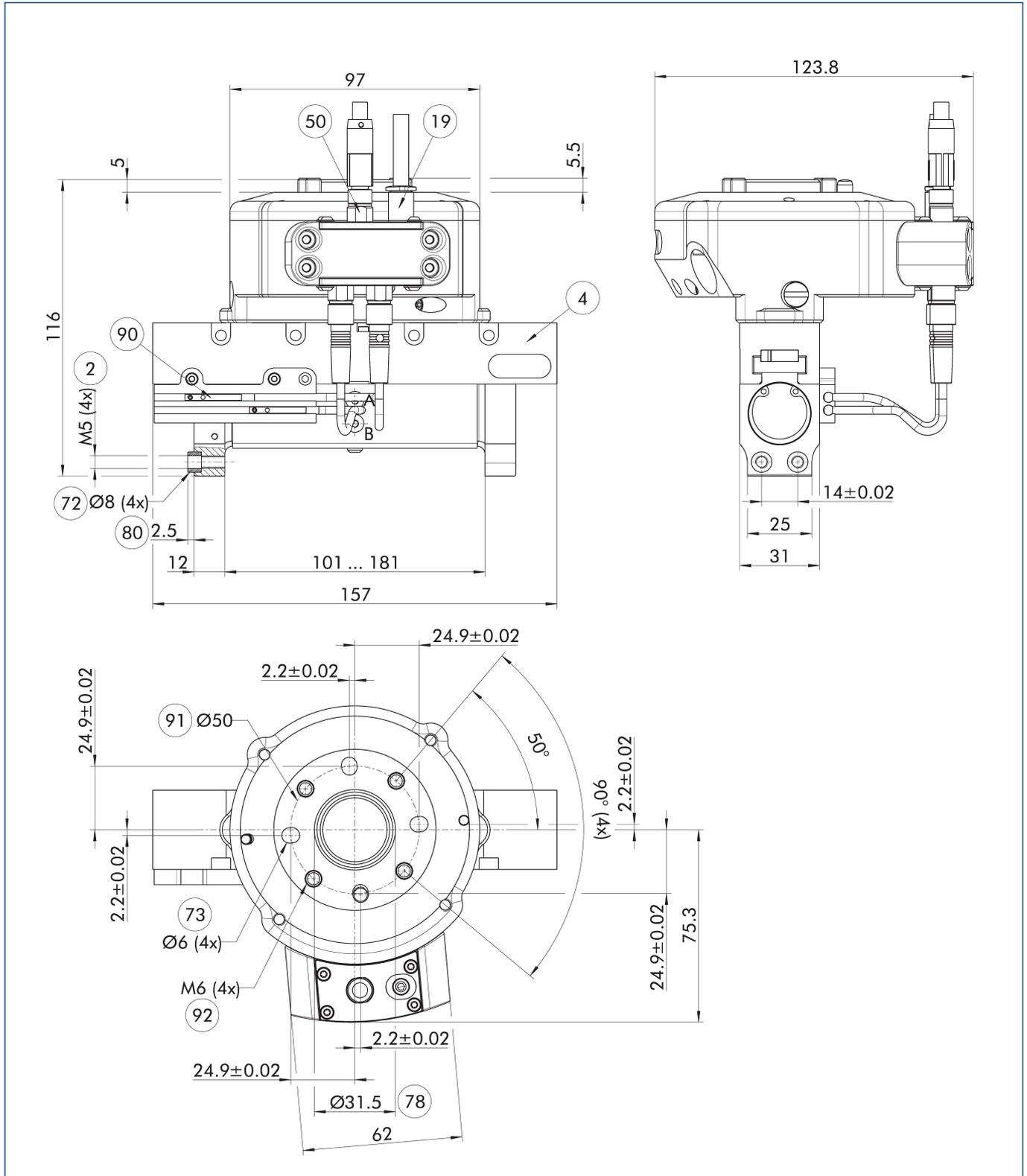
Description		EOA-UR3510-KGG 100-80	EOA-UR3510-PSH 22-1	EOA-UR3510-JGP 80-1	EOA-UR3510-JGP 100-1	EOA-UR3510-PGN-plus-P 80-1	EOA-UR3510-PGN-plus-P 100-1
ID		1327748	1327747	1348129	1348128	1327751	1327750
Function		Gripping	Gripping	Gripping	Gripping	Gripping	Gripping
Robot compatibility		UR 3/5/10/16	UR 3/5/10/16	UR 3/5/10/16	UR 3/5/10/16	UR 3/5/10/16	UR 3/5/10/16
Standard components		KGG 100-80	PSH 22-1	JGP 80-1	JGP 100-1	PGN-plus-P 80-1	PGN-plus-P 100-1
Stroke per jaw	[mm]	40	28	8	10	8	10
Max. gripping force	[N]	175	320	415	660	550	870
Weight	[kg]	1.2	1.7	1.33	1.72	1.38	1.8
Recommended workpiece weight	[kg]	0.9	1.6	2.1	3.3	2.75	4.35

① You can find more technical values in the catalog chapter for the respective standard component.

Description		EOA-UR3510-PZN-plus 64-1
ID		1327749
Function		Gripping
Robot compatibility		UR 3/5/10/16
Standard components		PZN-plus 64-1
Stroke per jaw	[mm]	6
Max. gripping force	[N]	580
Weight	[kg]	1.22
Recommended workpiece weight	[kg]	2.9

① You can find more technical values in the catalog chapter for the respective standard component.

Main view E0A-UR3510-KGG 100-80



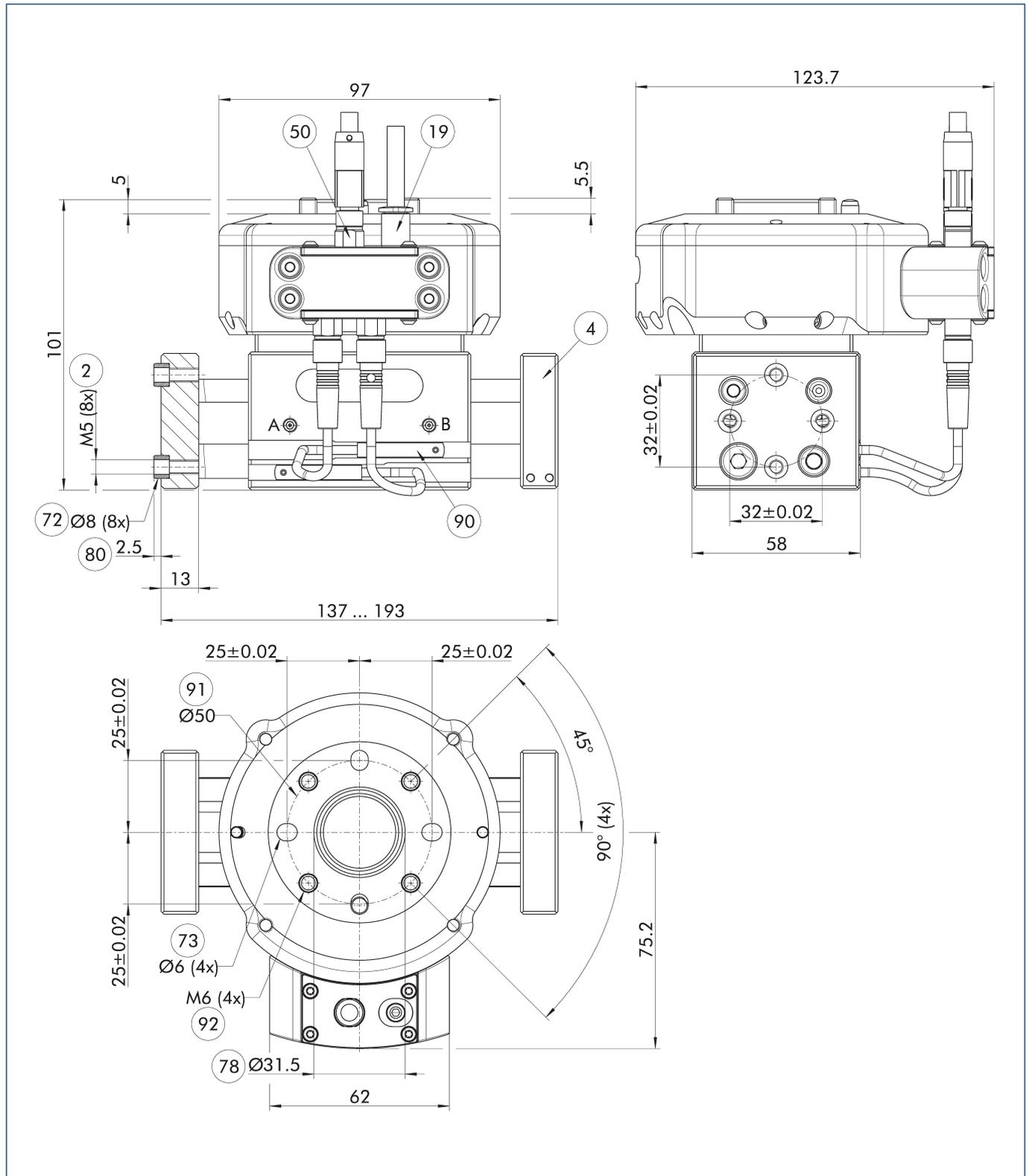
The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

- | | |
|------------------------------|---|
| ② Finger connection | ⑦⑧ Fit for centering |
| ④ Grippers | ⑧⑩ Depth of the centering sleeve hole in the counter part |
| ①⑨ Air connection | ⑨⑩ Sensor MMS 22.. |
| ⑤⑩ Electrical connection | ⑨① DIN ISO-9409 bolt circle |
| ⑦⑩ Fit for centering sleeves | ⑨② Through holes for screw connections |
| ⑦⑩ Fit for centering pins | |

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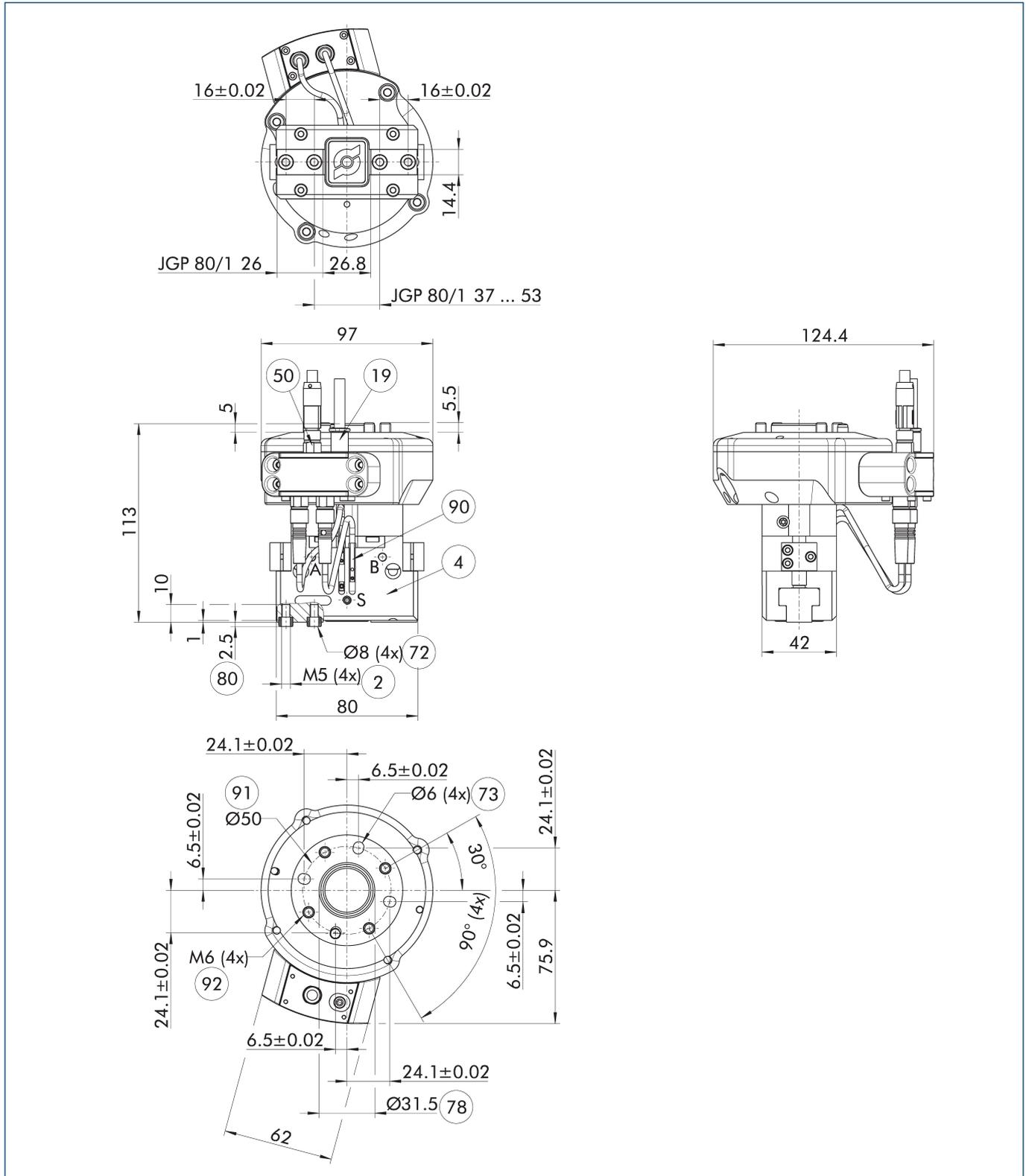
Main view EOA-UR3510-PSH 22-1



The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

- | | |
|------------------------------|---|
| ② Finger connection | ⑦⑧ Fit for centering |
| ④ Grippers | ⑧⑩ Depth of the centering sleeve hole in the counter part |
| ①⑨ Air connection | ⑨⑩ Sensor MMS 22.. |
| ⑤⑩ Electrical connection | ⑨⑩ DIN ISO-9409 bolt circle |
| ⑦⑩ Fit for centering sleeves | ⑨⑩ Through holes for screw connections |
| ⑦⑩ Fit for centering pins | |

Main view EOA-UR3510-JGP 80-1



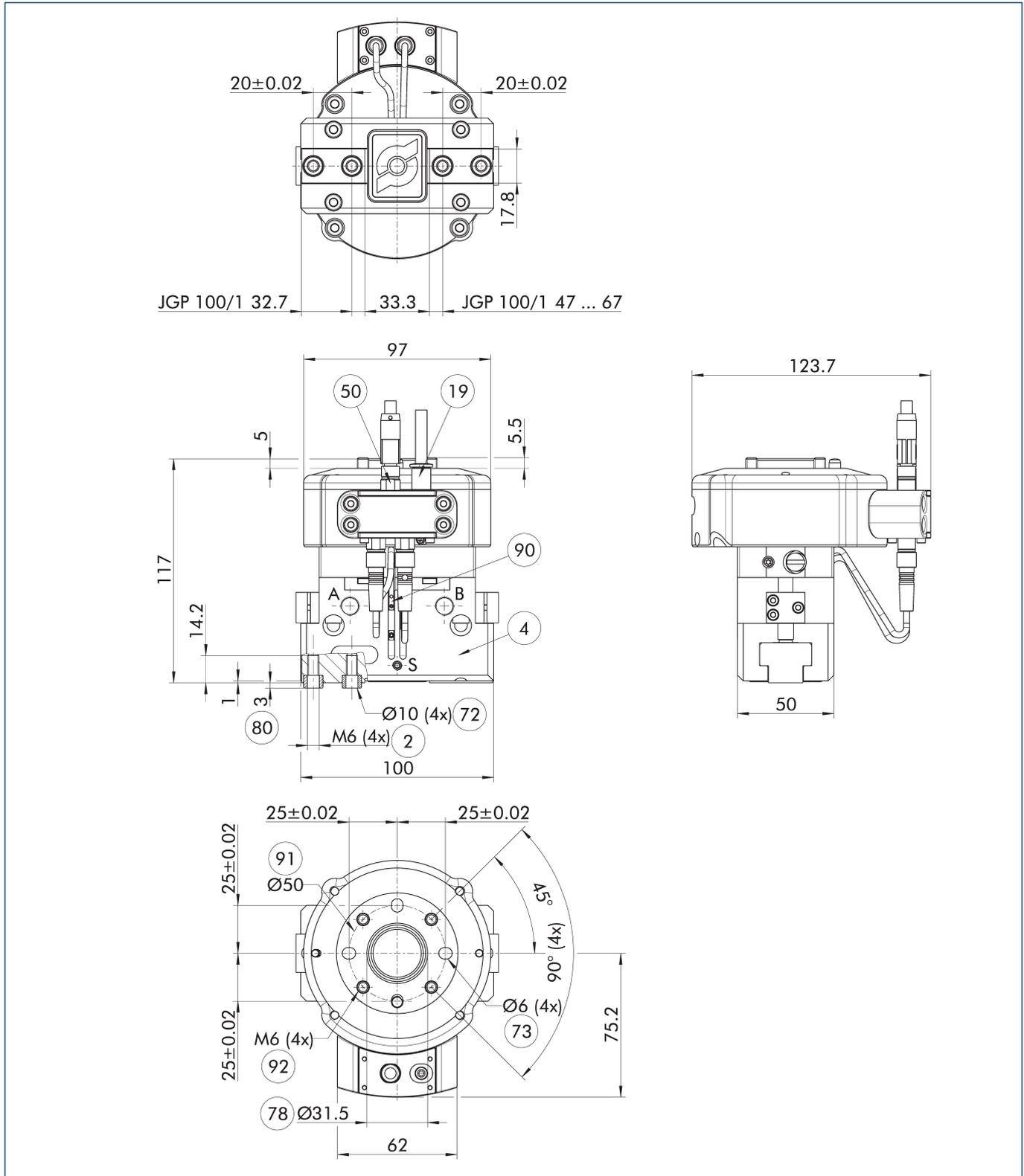
The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

- | | |
|------------------------------|--|
| ② Finger connection | ⑦⑧ Fit for centering |
| ④ Grippers | ⑧⑩ Depth of the centering hole in the counter part |
| ⑱ Air connection | ⑨⑩ Sensor MMS 22.. |
| ⑤⑩ Electrical connection | ⑨① DIN ISO-9409 bolt circle |
| ⑦② Fit for centering sleeves | ⑨② Through holes for screw connections |
| ⑦③ Fit for centering pins | |

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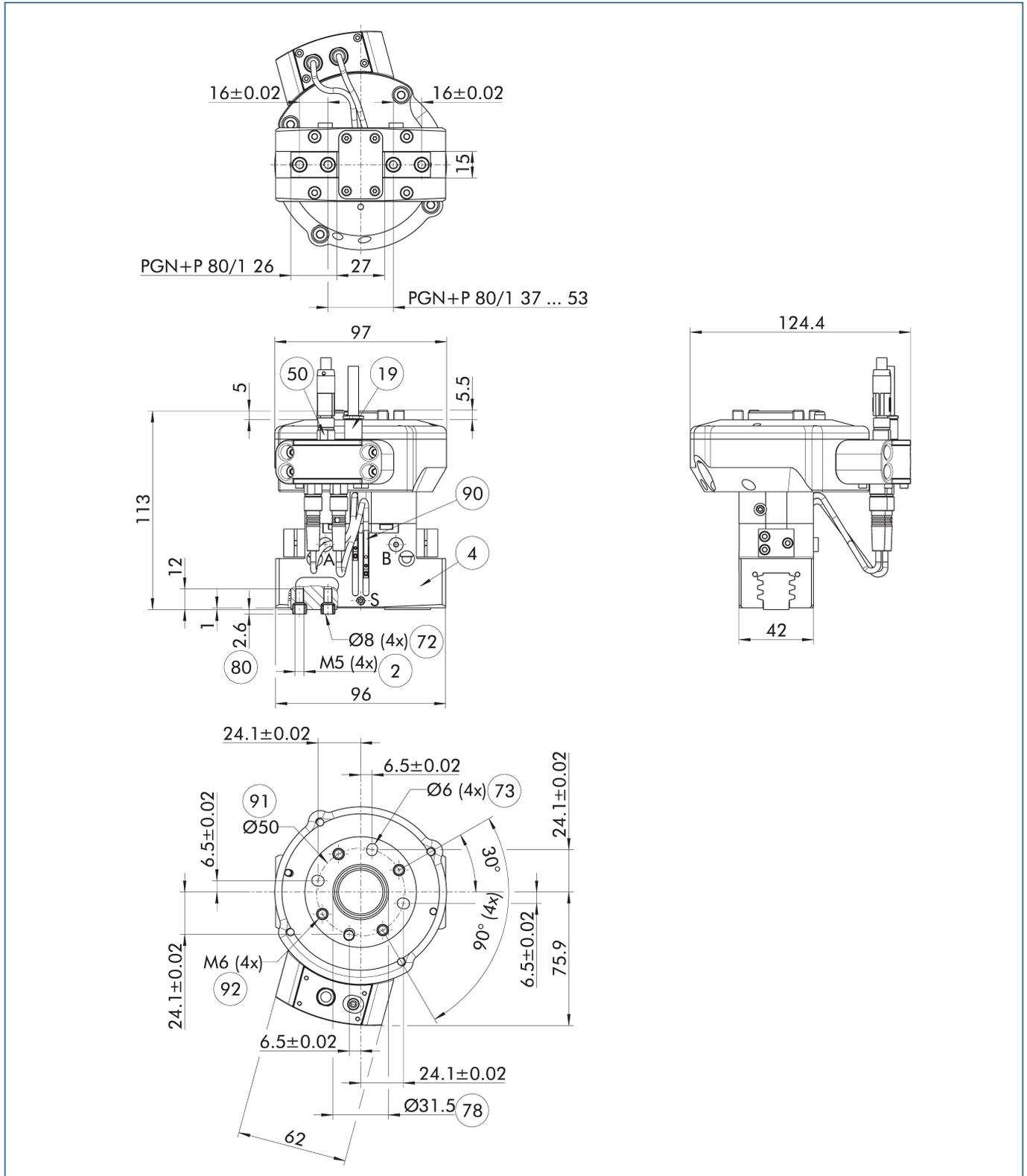
Main view EOA-UR3510-JGP 100-1



The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

- | | |
|------------------------------|---|
| ② Finger connection | ⑦⑧ Fit for centering |
| ④ Grippers | ⑧⑩ Depth of the centering sleeve hole in the counter part |
| ⑱ Air connection | ⑨⑩ Sensor MMS 22.. |
| ⑤⑩ Electrical connection | ⑨① DIN ISO-9409 bolt circle |
| ⑦② Fit for centering sleeves | ⑨② Through holes for screw connections |
| ⑦③ Fit for centering pins | |

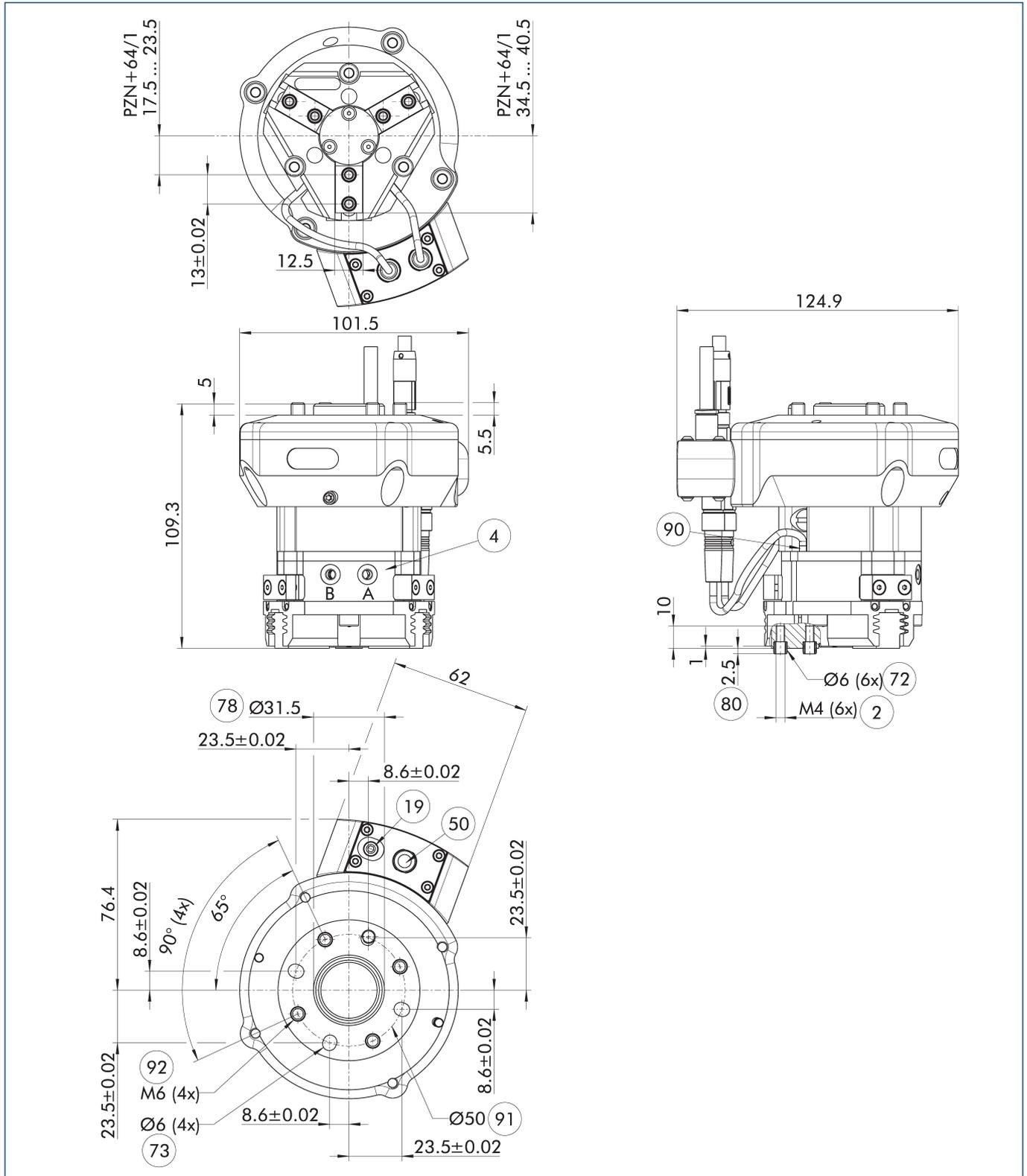
Main view EOA-UR3510-PGN-plus-P 80-1



The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

- | | |
|------------------------------|---|
| ② Finger connection | ⑦⑧ Fit for centering |
| ④ Grippers | ⑧⑩ Depth of the centering sleeve hole in the counter part |
| ⑱ Air connection | ⑨⑩ Sensor MMS 22.. |
| ⑤⑩ Electrical connection | ⑨① DIN ISO-9409 bolt circle |
| ⑦② Fit for centering sleeves | ⑨② Through holes for screw connections |
| ⑦③ Fit for centering pins | |

Main view EOA-UR3510-PZN-plus 64-1



The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

- | | |
|------------------------------|--|
| ② Finger connection | ⑦⑧ Fit for centering |
| ④ Grippers | ⑧⑩ Depth of the centering hole in the counter part |
| ①⑨ Air connection | ⑨⑩ Sensor MMS 22.. |
| ⑤⑩ Electrical connection | ⑨① DIN ISO-9409 bolt circle |
| ⑦⑩ Fit for centering sleeves | ⑨② Through holes for screw connections |
| ⑦⑩ Fit for centering pins | |

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Jens Lehmann, German goalkeeper legend, SCHUNK brand ambassador since 2012 for safe, precise gripping and holding.
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